CCS Technical Documentation
RH-26 Series Transceivers

2 - System Module

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Glossary of Terms

ACI	Accessory Control Interface
ADC	Analogue-Digital Converter
AEC	Acoustic Echo Canceller
AFC	Automatic Frequency Control
AGC	Automatic Gain Control
AIF	Application Interface
ALWE	Background noise suppressor
AMS	After Market Service
API	Application Programming Interface
ARM	Processor architecture
ASIC	Application Specific Integrated Circuit
BB	Baseband
CMT	Cellular Mobile Telephone (MCU and DSP)
CPU	Central Processing Unit
CTSI	Clocking Timing Sleep Interrupt
COG	Chip On Glass
CSP	Chip Scale Package
CSTN	Color Super Twisted Nematic
DAC	Digital-Analog Converter
DAI	Digital Audio Interface
DB	Dual band
DCN	Offset Cancellation control signal
DLL	Dynamic Link Library

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DRC	Dynamic Range Controller
DSP	Digital Signal Processor
EGSM	Extended – GSM
EFR	Enhanced Full Rate
EMC	Electromagnetic compatibility
EMI	Electromagnetic Interference
ESD	Electro Static Discharge
EXT RF	External RF
FBUS	Asynchronous Full Duplex Serial Bus
GPRS	General Packet Radio Service
GSM	Global System for Mobile communications
HS	Half Rate Speech
HSCSD	High Speed Circuit Switched Data
IC	Integrated Circuit
IHF	Integrated Hands Free
I/O	Input/Output
IRDa	Infrared Association
LCD	Liquid Crystal Display
LDO	Low Drop-Out
LNA	Low Noise Amplifier
MBUS	1-wire half duplex serial bus
MCU	Micro Controller Unit
MDI	MCU-DSP Interface
MFI	Modulator and Filter Interface

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PA	Transmit Power Amplifier
PC	Personal Computer
PCM	Pulse Code Modulation
PCM SIO	Synchronous serial bus for PCM audio transferring
PIFA	Planar Inverted F-antenna
PWB	Printed Wiring Board
RF	Radio Frequency
SIM	Subscriber Identity Module
UEM	Universal Energy Management
UI	User Interface
UPP	Universal Phone Processor
VCXO	Voltage Controlled Crystal Oscillator
VCTCXO	Voltage Controlled Temperature Compensated Crystal Oscillator.

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System Module

The system module TB6 consists of Radio Frequency (RF) and Baseband (BB) blocks. User Interface (UI) contains display, keyboard, bluetooth, IR link, HF/HS connector and audio parts. Part of the keyboard is implemented in a separate flip module, TF6.

The electrical part of the TB6 and half of the qwerty keyboard is located inside the flip module.

RH-26 includes a Pop-Port™ accessory interface. Both two and three wire type of chargers are supported. BL-5C Li-ion battery with nominal capacity of 850 mAh is used as main power source.

The baseband blocks provide the MCU, DSP, external memory interface and digital control functions in the UPP ASIC. Power supply circuitry, charging, audio processing and RF control hardware are located in the UEM ASIC.

The purpose of the RF block is to receive and demodulate the radio frequency signal from the base station and to transmit a modulated RF signal to the base station.

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Baseband

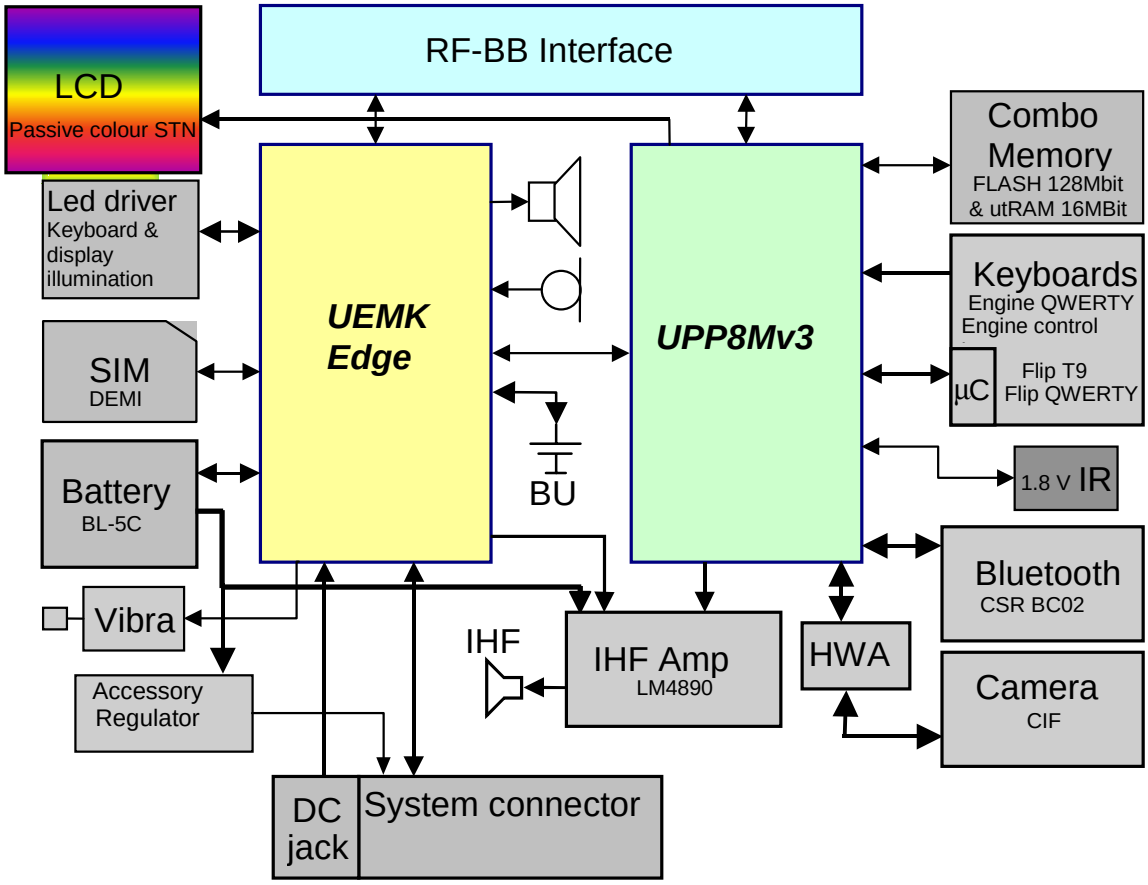
Technical summary

The main functionality of the baseband is implemented into two ASICs:

- UPP (Universal Phone Processor) and

- UEMK Edge (Universal Energy Management)

Figure 1: Baseband block description



Baseband is running from power rails 2.8V analog voltage and 1.8V I/O voltage. UPP core voltages can be programmed to 1.053V, 1.35V, 1.57V (default) and 1.8V. UEMK includes a 6-linear LDO (low drop-out) regulator for baseband and 7 regulators for RF. It also includes 4 current sources for biasing purposes and internal usage. UEMK also includes SIM interface, which supports both 1.8V and 3V SIM cards.

The baseband architecture supports a power saving function called "sleep mode". This sleep mode shuts off the VCTCXO, which is used as system clock source for both RF and baseband. During the sleep mode, the system runs from a 32 kHz crystal. The phone is waken up by a timer running from this 32 kHz clock supply or from external interrupt. The sleeping time is determined by network parameters. The sleep mode is entered when both the MCU and the DSP are in standby mode and the normal VCTCXO clock has been switched off. Bluetooth has its own sleep period that is not aligned with phone sleep.

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A real time clock function is integrated into the UEMK, which utilises the same 32kHz clock supply as the sleep clock. A backup power supply is provided for the RTC-battery, which keeps the real time clock running when the main battery is removed. The backup power supply is a rechargeable surface mounted cell capacitor. The backup time with the cell capacitor is 15 minutes minimum.

The interface between the baseband and the RF section is mainly handled by a UEMK ASIC**.** UEMK provides A/D and D/A conversion of the in-phase and quadrature receive and transmit signal paths and also A/D and D/A conversions of received and transmitted audio signals to and from the user interface. The UEMK supplies the analog TXC and AFC signals to the RF section according to the UPP DSP digital control. Data transmission between the UEMK and the UPP is implemented using two serial busses, DBUS for DSP and CBUS for MCU. There are also separate signals for PDM coded audio. Digital speech processing is handled by the DSP inside UPP ASIC. UEMK is a dual voltage circuit, the digital parts are running from the baseband supply 1.8V and the analogue parts are running from the analogue supply 2.78V also VBAT is directly used by some specific blocks.

The baseband supports both internal and external microphone inputs and speaker outputs. Input and output signal source selection and gain control is done by the UEMK according to control messages from the UPP. Keypad tones, DTMF, and other audio tones are generated and encoded by the UPP and transmitted to the UEMK for decoding. An external vibra alert control signal is generated by the UEMK with separate PWM output.

RH-26 has two external serial control interfaces: FBUS and MBUS. FBUS can be accessed through service test pattern and Pop-Port^{TM} System Connector. FBUS interface and MBUS can be accessed through the service test pattern.

EMC shielding is implemented using soldered metal cans. Heat generated by the circuitry is conducted out via ground planes located in the PWB.

The RH-26 PWB is implemented into an 8-layer selective OSP coated PWB using buried via technology.

Main technical specifications

DC characteristics

Regulators and supply voltage ranges

Table 1: Baseband regulators

Signal	Min	Nom	Max	Note
VANA	2.70V	2.78V	2.86V	I_{max} = 80mA
VFLASH1	2.70V	2.78V	2.86V	I_{max} = 70mA I_{sleep} = 1.5mA
VFLASH2	2.70V	2.78V	2.86V	I_{max} = 40mA

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VSIM	1.745V 2.91V	1.8V 3.0V	1.855V 3.09V	I_{max} = 25mA I_{sleep} = 0.5mA
VIO	1.72V	1.8V	1.88V	I_{max} = 150mA I_{sleep} = 0.5mA
VCORE	1.0V 1.283V 1.492V 1.710V	1.053V 1.35V 1.57V 1.8V	1.106V 1.418V 1.649V 1.890V	I_{max} = 200mA I_{sleep} = 0.2mA Default value 1.57V

Table 2: Accessory regulator

Signal	Min	Nom	Max	Note
Vout	2.70V	2.78	2.86V	I_{max} = 150mA $I_{quiescent}$ < 1.5µA Enable controlled through GenIO(0)

Table 3: RF regulators

Signal	Min	Nom	Max	Note
VR1A / VR1B	4.6V	4.75V	4.9V	I_{max} = 10mA
VR2	2.70V 3.20V	2.78V 3.3V	2.86V 3.40V	I_{max} = 100mA
VR3	2.70V	2.78V	2.86V	I_{max} = 20mA
VR4	2.70V	2.78V	2.86V	I_{max} = 50mA I_{sleep} = 0.1mA
VR5	2.70V	2.78V	2.86V	I_{max} = 50mA I_{sleep} = 0.1mA
VR6	2.70V	2.78V	2.86V	I_{max} = 50mA I_{sleep} = 0.1mA
VR7	2.70V	2.78V	2.86V	I_{max} = 45mA

Table 4: Current sources

Signal	Min	Nom	Max	Note
IPA1 and IPA2		0mA – 5mA		Programmable, +/-6% $V_{IPA1,2}$ = 0V - 2.7V
IPA3 and IPA4	95µA	100µA	105µA	$V_{IPA3,4}$ = 0V - 2.7V (used internally in the UEMK)

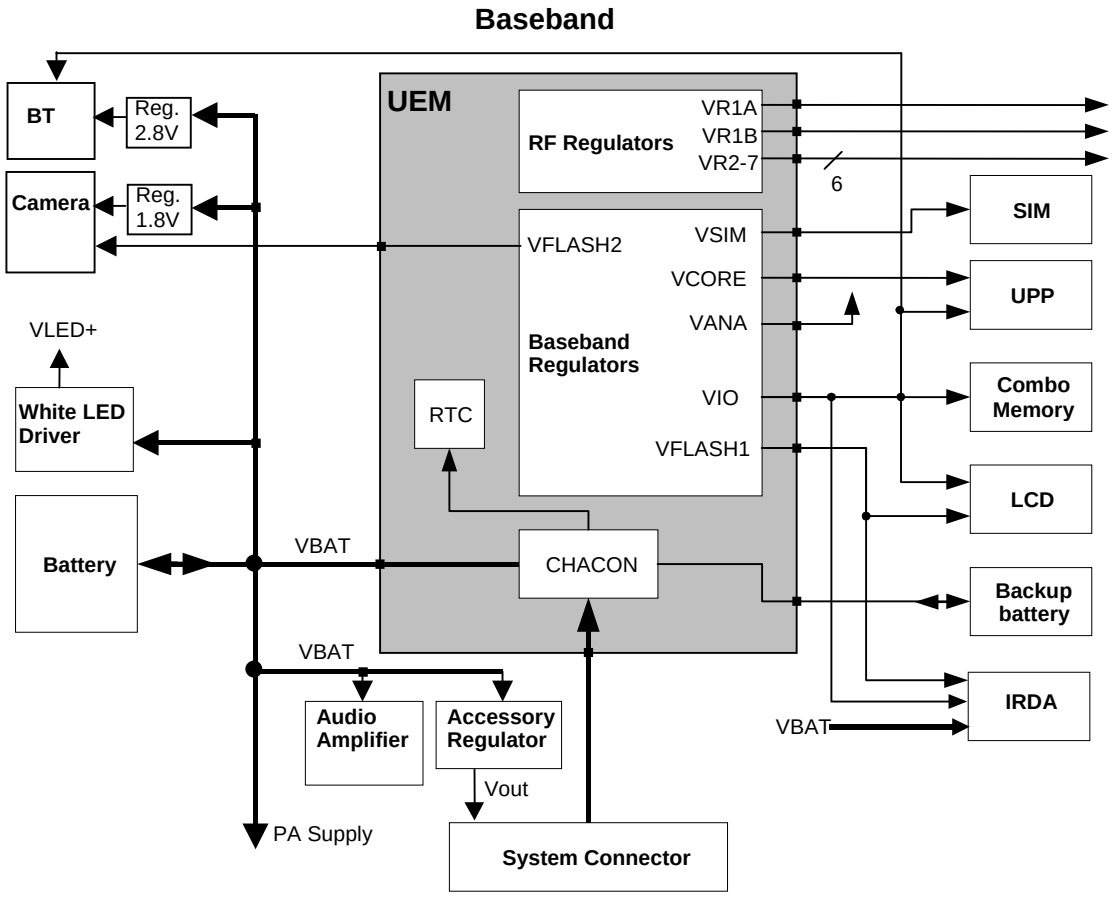
Table 5: External BT regulator characteristics

Power source	Voltage (V)			Max. load (mA)	Function
	Min	Typ	Max		
VBth	2.72	2.80	2.86	70mA	From external 2.8V regulator
VIO	1.72	1.80	1.88	10 mA	I/O-voltage to ensure compatible IO levels.

Table 6: External camera regulator characteristics

Power source	Voltage (V)			Max. load (mA)	Function
	Min	Typ	Max		
VCAMDIG	1.72	1.80	1.88	150 mA	I/O-voltage to ensure compatible IO levels.

Figure 2: Power distribution diagram



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Internal signals and connections

Table 7: Internal microphone

Signal	Min	Nom	Max	Condition	Note
MICP			200mV$_{pp}$	AC	2.2kΩ to MIC1B
	2.0 V	2.1 V	2.25 V	DC	
MICN	2.0V	2.1V	2.25V	DC	

Table 8: Internal speaker

Signal	Min	Nom	Max	Condition	Note
EARP	0.75V	0.8V	2.0 V$_{pp}$ 0.85V	AC DC	Differential output (V$_{diff}$ = 4.0 V$_{pp}$)
EARN	0.75V	0.8V	2.0 V$_{pp}$ 0.85V	AC DC	

Table 9: Bluetooth clock specifications

Bluetooth clock	Specification
BTClk	Single ended input
Frequency	26MHz (VCTCXO)
Min. level	200 mVpp
Max. level	1.8 Vpp (VIO)
Input impedance	Input impedance < 4 pF and >10kohm
Phase noise	Max. –129 dBc/Hz @ 1 kHz at 26 MHz
Phase Jitter	15ps rms
Settling time	Max. 5ms (BTHostWakeUp -> BTClk stabile)

External signals and connections

Table 10: UI connector

Pin	Signal	Min	Nom	Max	Condition	Note
16	VDDI	1.72V	1.8V	1.88V		Logic voltage supply Connected to VIO
15	XRES	0.7*VDDI 0		VDDI 0.3*VDDI	Logic '1' Logic '0'	Reset Active low
		1us			t_{rw}	Reset active
14	SDA	0.7*VDDI 0		VDDI 0.3*VDDI	Logic '1' Logic '0'	Serial data
		100ns			t_{sds}	Data setup time
		100ns			t_{sdh}	Data hold time
13	SCLK	0.7*VDDI 0		VDDI 0.3*VDDI 6.5MHz	Logic '1' Logic '0' Max frequency	Serial clock input
		250ns			t_{scyc}	Clock cycle
		100ns			t_{shw}	Clock high
		100ns			t_{slw}	Clock low
12	CXS	0.7*VDDI 0		VDDI 0.3*VDDI	Logic '1' Logic '0'	Chip select Active low
		60ns			t_{css}	CXS low before SCLK rising edge
		100ns			t_{csh}	CXS low after SCLK rising edge
11	GND		0V			
10	GND		0V			
9	GND		0V			
8	GND		0V			
7	GND		0V			
6	GND		0V			
5	VDD	VDD	2.70V	2.78V	2.86V	Supply Voltage. Connected to VFLASH1
4	GND		0V			
3	GND		0V			
2	VLED-	0V	 0.5V		LED off LED on	Feedback Voltage to LED Driver

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1	VLED+	0V 9V			LED off LED on	Supply Voltage for LEDs

Table 11: FLIP connector

Pin	Signal	Min	Nom	Max	Condition	Note
1	FLIPCLK	0.7*VIO 0		VIO 0.3*VIO	Logic '1' Logic '0'	Bus clock for flip module
2	VBAT		3.7V	4.2V		Supply for flip µC
3	FLIPDATA	0.7*VIO 0		VIO 0.3*VIO	Logic '1' Logic '0'	I/O data for flip module

Table 12: DC connector

Pin	Signal	Min	Nom	Max	Condition	Note
1	VCHAR		11.1V_{peak}	16.9 V_{peak} 7.9 V_{RMS} 1.0 A_{peak}	Standard charger	Charger positive input
		7.0 V_{RMS}	8.4 V_{RMS}	9.2 V_{RMS} 850 mA	Fast charger	
2	CHGND		0			Charger ground

Table 13: Pop-Port™ system connector

Pin	Signal	Description	Spectral Range	U/I levels	Impedance	Notes
1	CHARGE	V Charge	DC	0-9 V / 0.85 A		
2	GND	Charge GND		0.85 A	100 mΩ	(PWB + conn.)
3	ACI	ACI	1 kbit/s	Dig 0 / 2.78V	47 Ω	Insertion & removal detection
4	VOUT	DC out	DC	2.78V / 70mA	100 mΩ	(PWB + conn.) 200mW
5	NC	DC in	DC	4.375-5.25V		
6	FBUS RX		FBUS 115k	FBus 0 / 2.78V	33 Ω	
7	FBUS TX		FBUS 115k	FBus 0 / 2.78V	33 Ω	
8	GND	Data GND				
9	XMIC N	Audio in	300 - 8k	1Vpp & 2.78V		DC
10	XMIC P	Audio in	300 - 8k	1Vpp & 2.78V		DC
11	HSEAR N	Audio out	20 - 20k	1Vpp	10 Ω	
12	HSEAR P	Audio out	20 - 20k	1Vpp	10 Ω	
13	NC					Not Connected

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14	NC					Not Connected

Table 14: SIM connector

Pin	Name	Parameter	Min	Typ	Max	Unit	Notes
1	VSIM	1.8V SIM Card	1.62	1.8	1.98	V	Supply voltage
		3V SIM Card	2.7	3.0	3.3	V	
2	SIMRST	1.8V SIM Card	0.8xVSIM 0		VSIM 0.2xVSIM	V	SIM reset (output)
		3V SIM Card	0.8xVSIM 0		VSIM 0.2xVSIM	V	
3	SIMCLK	Frequency		3.25		MHz	SIM clock
		Trise/Tfall			50	ns	
		1.8V Voh 1.8V Vol	0.7xVSIM 0		VSIM 0.2xVSIM	V	
		3V Voh 3V Vol	0.7xVSIM 0		VSIM 0.2xVSIM	V	
4	DATA	1.8V Voh 1.8V Vol	0.7xVSIM 0		VSIM 0.3	V	SIM data (output)
		3V Voh 3V Vol	0.7xVSIM 0		VSIM 0.4	V	
		1.8V Vih 1.8V Vil	0.7xVSIM -0.3		VSIM +0.3 0.2xVSIM	V	SIM data (input) Trise/Tfall max 1us
		3V Vil 3V Vil	0.7xVSIM -0.3		VSIM +0.3 0.2xVSIM		
5	NC						Not connected
6	GND	GND	0		0	V	Ground

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Baseband functional description

Modes of operation

RH-26 baseband engine has six different functional modes:

- No supply
- Back-up
- Acting Dead
- Active
- Sleep
- Charging

No supply

In NO_SUPPLY mode, the phone has no supply voltage. This mode is a result of disconnection of the main and backup batteries or low battery voltage level in both of the batteries.

Phone is exiting from *NO_SUPPLY* mode when sufficient battery voltage level is detected. Battery voltage can rise either by connecting a new battery with $VBAT > V_{MSTR+}$ or by connecting charger and charging the battery above V_{MSTR+}.

Back-up

In BACK_UP mode, the backup battery has sufficient charge but the main battery can be disconnected or empty ($VBAT < V_{MSTR}$ *and* $VBACK > VBU_{COFF}$).

VRTC regulator is disabled in *BACK_UP* mode. VRTC output is supplied without regulation from backup battery (VBACK). All the other regulators are disabled in *BACK_UP* mode.

Acting dead

If the phone is off when the charger is connected, the phone is powered on but enters a state called "*Acting Dead*". To the user, the phone acts as if it was switched off. A battery charging alert is given and/or a battery charging indication on the display is shown to acknowledge the user that the battery is being charged.

Active

In the ACTIVE mode, the phone is operates normally, scanning for channels, listening to a base station, transmitting and processing information. There are several sub-states in the active mode depending on if the phone is in burst reception, burst transmission, if DSP is working, etc.

In the *Active* mode, the RF regulators are controlled by SW, which writes the desired settings into UEMK's registers: VR1A can be enabled or disabled. VR2 can be enabled or dis-

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abled and its output voltage can be programmed to be 2.78V or 3.3V. VR4 -VR7 can be enabled, disabled, or forced into low quiescent current mode. VR3 is always enabled in the Active mode.

Sleep mode

SLEEP mode is entered when both MCU and DSP are in stand–by mode. Sleep is controlled by both processors. When SLEEPX low signal is detected, UEMK enters the SLEEP mode. VCORE, VIO and VFLASH1 regulators are put into low quiescent current mode. All the RF regulators are disabled in SLEEP. When SLEEPX=1 is detected, UEMK enters the ACTIVE mode, which activates all functions.

The sleep mode is exited either by the expiration of a sleep clock counter in the UEMK or by some external interrupt, generated by a charger connection, key press, headset connection, etc.

In the sleep mode, VCTCXO is shut down and a 32 kHz sleep clock oscillator is used as a reference clock for the baseband.

Charging

Charging can be performed in any operating mode. The battery type/size is indicated by a resistor inside the battery pack. The resistor value corresponds to a specific battery capacity. This capacity value is related to the battery technology as different capacity values are achieved by using different battery technology.

The battery voltage, temperature, size and current are measured by the UEMK controlled by the charging software running in the UPP.

The charging control circuitry inside the UEMK controls the charging current delivered from the charger to the battery. The battery voltage rise is limited by turning the UEMK switch off when the battery voltage reaches 4.2 V. Charging current is monitored by measuring the voltage drop across a 220 mΩ resistor.

Battery

850 mAh Li-ion battery pack BL-5C is used in RH-26.

Table 15: BL–5C characteristics

Description	Value
Nominal discharge cut-off voltage	3.1V
Nominal battery voltage	3.7V
Nominal charging voltage	4.2V
Maximum charger output current	850 mA
Minimum charger output current	200 mA
Discharge Temperature	-20 °C... +70 °C

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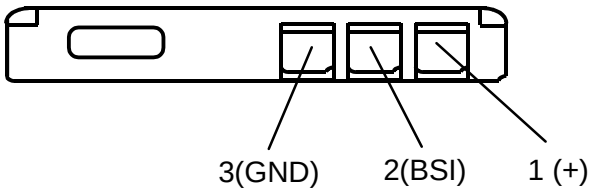
Charging Temperature	-30 °C... +60 °C

Table 16: Pin numbering of battery pack

Signal name	Pin number	Function
VBAT	1	Positive battery terminal
BSI	2	Battery capacity measurement (fixed resistor inside the battery pack)
GND	3	Negative/common battery terminal

Figure 3: BL-5C battery pack contacts



The BSI fixed resistor value indicates type and default capacity of a battery. NTC-resistor measures the battery temperature.

Temperature and capacity information is needed for the charge control. BSI is connected to a pin in the battery connector. BTEMP is connected to NTC resistor. NTC is located on the engine PWB. Phone has 100 kΩ pull-up resistors for these lines so that they can be read by A/D inputs in the phone.

Table 17: BSI resistor values

Parameter	Min	Typ	Max	Unit	Notes
Battery size indicator resistor BSI		75		kΩ	Battery size indicator (BL-5C) Tolerance ±1%
	6.7	6.8	6.9	kΩ	Test mode resistor value
	3.2	3.3	3.4	kΩ	Local mode resistor value

Table 18: BTEMP NTC resistor properties

Parameter	Min	Typ	Max	Unit	Notes
NTC resistor BTEMP		47		kΩ	Battery temperature indicator (NTC pulldown) ±5% @ 25°C
		4050		K	Beta value (B). Tolerance ±3%, +25°C / +85°C

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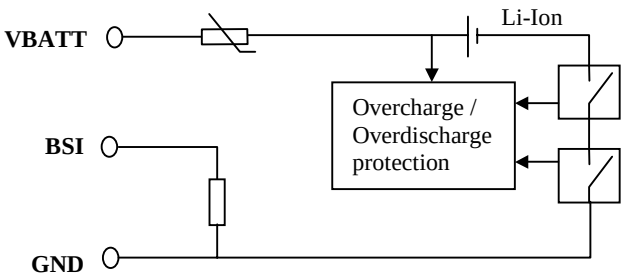
Figure 4: Interconnection diagram



Charging

Supported chargers are ACP-7, ACP-8, ACP-9, ACP-12, LCH-8, LCH-9 and LCH-12.

Charging is controlled by the UEMK ASIC. External components are needed for current sensing, EMC, reverse polarity and transient protection of the input to the baseband module. The charger is connected to the system connector interface. The RH-26 baseband is designed to support DCT3 chargers. Both 2- and 3-wire type chargers are supported.

The operation of the charging circuit has been specified in such a way as to limit the power dissipation across the charge switch and to ensure safe operation in all modes.

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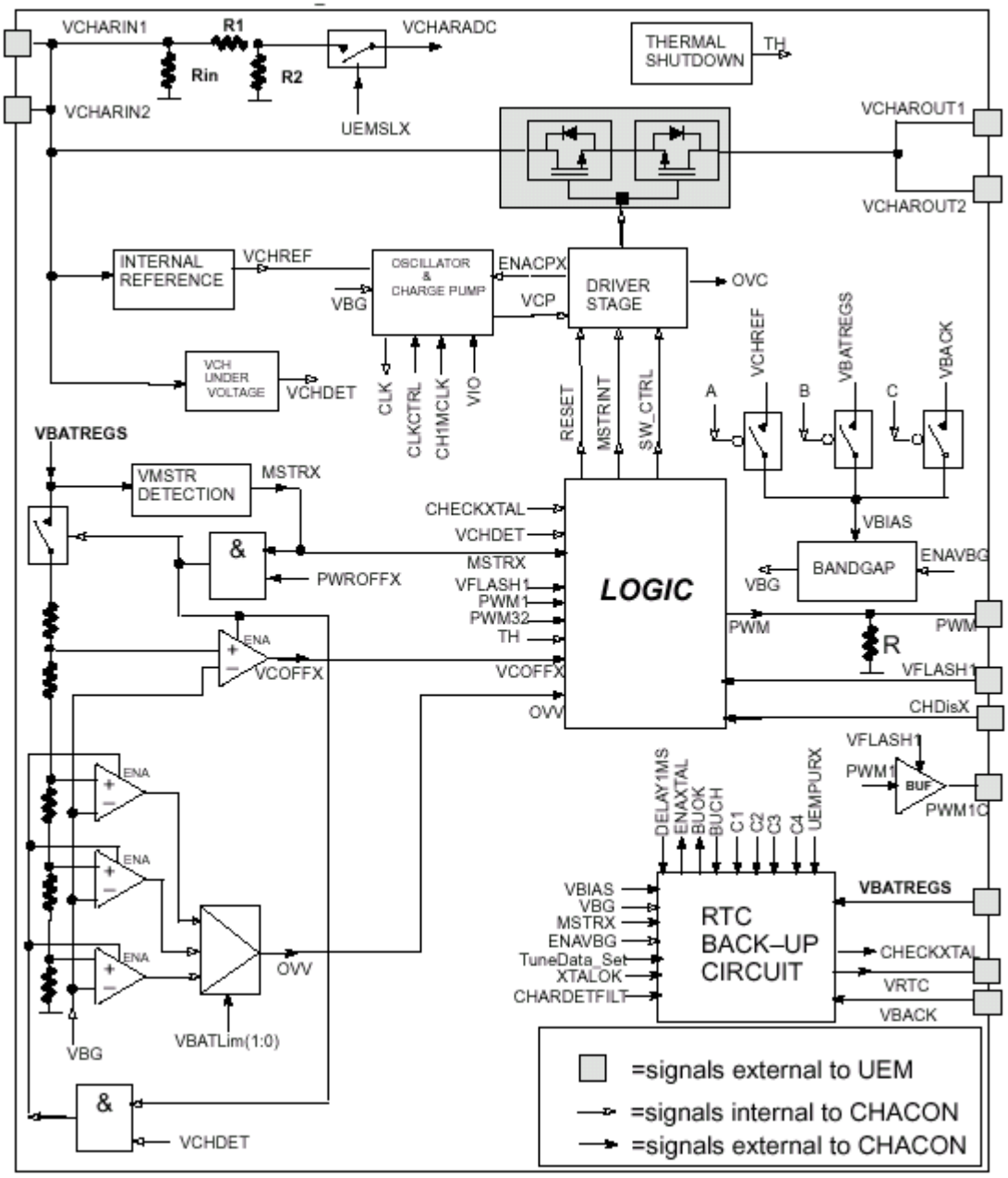
Figure 5: UEMK charging circuitry



Charger detection

When connected, a charger creates voltage on VCHAR input of the UEMK. When VCHAR input voltage level is detected to have risen above VCH_{DET+} threshold by CHACON, the charging process starts. VCHARDET signal is generated to indicate the presence of the charger. The charger identification is controlled by EM SW.

The charger recognition is initiated when the EM SW receives a "charger connected" interrupt. The algorithm consists of the following three steps:

1 Check that the charger output (voltage and current) is within safety limits.

2 Identify the charger as a two-wire or three-wire charger.

3 Check that the charger is within the charger window.

If the charger is accepted and identified, the appropriate charging algorithm is initiated.

Charge control

In the active mode, charging is controlled by UEMK's digital part. Charging voltage and current monitoring is used to limit charge into safe area. For that reason, UEMK has programmable charging cut–off limits VBATLim $_{1,2L,2H}$ (3.6V / 5.0V /5.25V). Maximum charging current is limited to 1.2 A. Default for VBATLim is 3.6V.

VBATLim $_{1,2L,2H}$ are designed with hysteresis. When the voltage rises above VBATLim $_{1,2L,2H}$ + charging is stopped by turning charging switch OFF. There is no change in operational mode. After voltage has decreased below VBAT-Lim–, charging re–starts.

If VBAT is detected to have risen above the programmed limit, the output signal OVV is set to '1' by CHACON. If charging current limit is reached, OVC output is set to '1' by CHACON (disabled by EM SW).

Pulse–width–Modulated (PWM) control signals PWM1 and PWM32 are generated by UEMK's digital part to CHACON block. There are two PWM frequencies in use depending on the type of the charger: standard charger 1Hz, fast charger 32Hz. Duty cycle range is from 0% to 100%.

Supported chargers

Transformer type chargers

The standard charger (ACP-7) has a mains transformer with a typical output impedance of 11.1 Ω. It has a full-wave rectified output with no smoothing capacitor on the output. As charging circuitry gets its supply from the charger, voltage UEMK must be able to generate supply voltage for needed control from full wave rectified charger input.

Table 19: ACP–7 characteristics

Description	Min.	Typ.	Max.	Unit
Output impedance (at +23*C)	10.1	11.1	12.1	W
Output voltage (average) with 5 kΩ load	7.25	7.6	7.95	V
Output voltage (peak) with 5 kΩ load and with max. (Nominal +20%) mains voltage.			16.9	V

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Figure 6: Transformed type charger window (U/I curve)

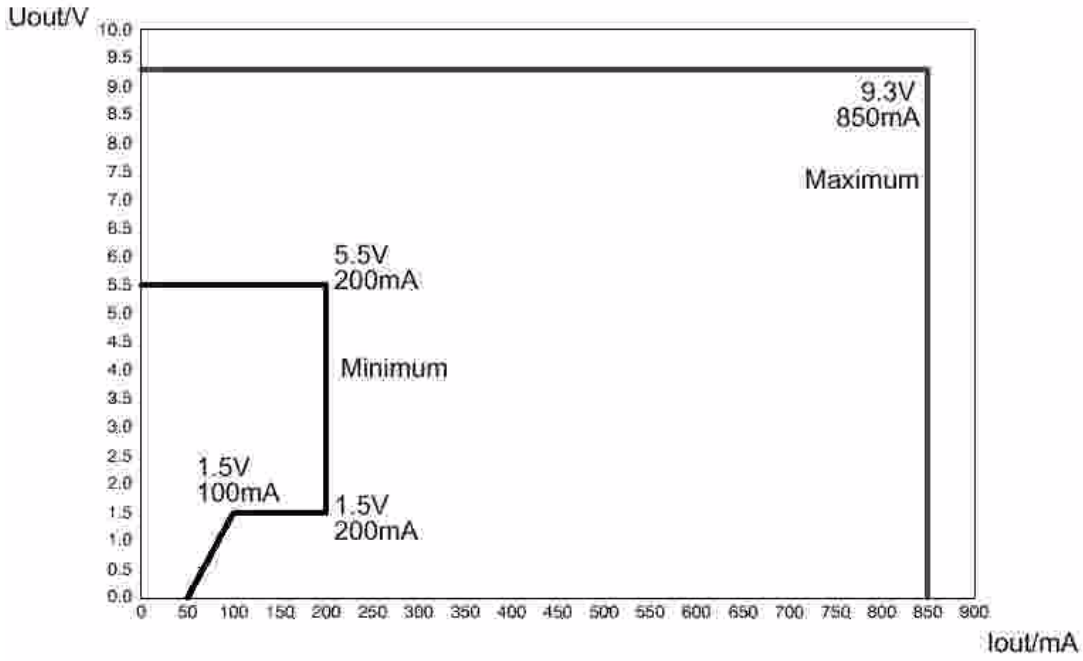
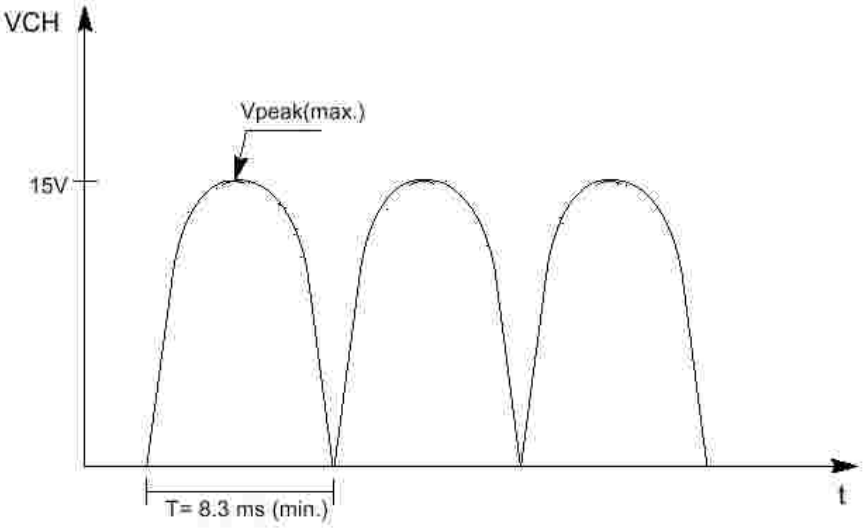


Figure 7: Full-wave rectified output of standard charger



Current limited constant voltage chargers

2- and 3-wire current limited constant voltage chargers are supported.

3-wire chargers:

- ACP-9
- LCH-9

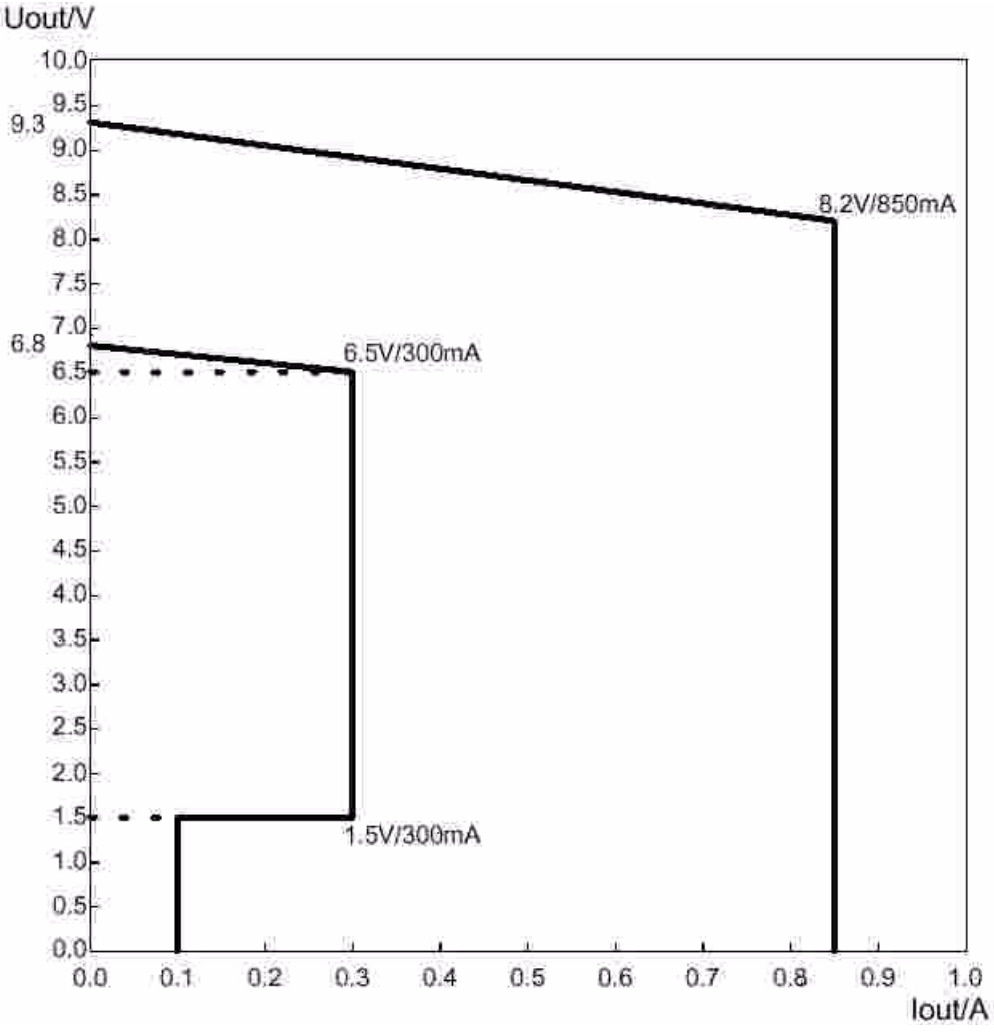
2-wire chargers:

- ACP-8
- ACP-12
- LCH-8
- LCH-12

The 3-wire chargers have a 3-wire interface to the phone, 2 power and 1 control. To control the charger output voltage, the wire carries a 32Hz digital pulse width modulated signal generated by the phone. In RH-26, 32 Hz PWM for the charger is connected to GND inside the bottom connector. This sets full charger output voltage and equals to 0% PWM from the charger point of view.

The output capacity of a fast charger is typically 1000uF. The cable impedance (from output capacitor to the phone) is typically 0.5 Ω.

Figure 8: U/I specification at control input 0% or without control



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Charger interface protection

In order to ensure safe operation with all chargers and in misuse/fail situations, the charger interface is protected by using a transient voltage suppressor (TVS) and 1.5A fuse. TVS used in RH-26 is a 16V@175W device.

Table 20: TVS characteristics

Parameter	Value
Breakdown voltage (VBR)	17.8 Vmin (at IT 1.0mA)
Reverse standoff voltage (VR)	16V
Max reverse leakage current at VR (IR)	5uA
Max peak impulse current (Ipp) (at Ta=25*C and peak impulse current waveform: 10/1000us)	7A
Max clamping voltage at Ipp (Vc)	26V

Power up and reset

Power up and reset is controlled by the UEMK ASIC. RH-26 baseband can be powered up in the following ways:

- Press power button, meaning grounding the PWRONX pin on UEMK.
- Connect the charger to the charger input.
- Supply battery voltage to the battery pin.
- RTC Alarm, the RTC has been programmed to give an alarm.

After receiving one of the above signals, the UEMK counts a 20ms delay and then enters its reset mode. The watchdog starts up, and if the battery voltage is greater than Vcoff+, a 200ms delay is started to allow references to settle. After this delay elapses, the VFLASH1 regulator is enabled. 500us later VR3, VANA, VIO and VCORE are enabled. Finally, the PURX line is held low for 20 ms. This reset, PURX, is fed to the baseband ASIC UPP. Resets are generated for the DSP and the MCU. During this reset phase the UEMK forces the VCXO regulator on, regardless of the status of the sleep control input signal to the UEMK. The sleep signal from the ASIC is used to reset the flash during the power up mode and to put the flash in the power down mode during sleep. All baseband regulators are switched on at the UEMK power on, except the SIM regulator that is controlled by the MCU. The UEMK internal watchdog is running during the UEMK reset state, with the longest watchdog time selected. If the watchdog expires, the UEMK returns to power off state. The UEMK watchdog is internally acknowledged at the rising edge of the PURX signal in order to always give the same watchdog response time to the MCU.

Power up with PWR key

When the power on key is pressed, the UEMK enters the power up sequence as described in the previous paragraph. Pressing the power key causes the PWRONX pin on the UEMK

to be grounded. The UEMK PWRONX signal is not part of the keypad matrix. The power key is only connected to the UEMK. This means that when pressing the power key, an interrupt is generated to the UPP that starts the MCU. The MCU then reads the UEMK interrupt register and notices that it is a PWRONX interrupt. The MCU now reads the status of the PWRONX signal using the UEMK control bus, CBUS. If the PWRONX signal stays low for a certain time, the MCU accepts this as a valid power on state and continues with the SW initialization of the baseband. If the power on key does not indicate a valid power on situation, the MCU powers off the baseband.

Power up when charger is connected

In order to be able to detect and start charging in a case where the main battery is fully discharged (empty), and hence UEMK has no supply (NO_SUPPLY or BACKUP mode of UEMK), charging is controlled by the START-UP CHARGING circuitry.

Whenever VBAT level is detected to be below master reset threshold (VMSTR-), charging is controlled by START_UP charge circuitry. Connecting a charger forces VCHAR input to rise above charger detection threshold, VCHDET+. Upon detection, start-up charging is started. UEMK generates 100mA constant output current from the connected charger's output voltage. As battery charges, its voltage rises, and when VBAT voltage level is higher than master reset threshold limit (VMSTR+), charge is terminated.

Charge control block (CHACON) monitors the VBAT voltage level. MSTRX='1' output reset signal (internal to UEMK) is given to UEMK's RESET block when VBAT>VMSTR+. UEMK enters the reset sequence.

If VBAT is detected to fall below VMSTR- during start-up charging, charging is cancelled. Charging will restart, if new rising edge on VCHAR input is detected (VCHAR rising above VCHDET+).

Power up when battery is connected

Baseband can be powered up by connecting battery with sufficient voltage. Battery voltage has to be over UEMK internal comparator threshold level, Vcoff+. When battery voltage is detected, UEMK enters the reset sequence.

Phone can be powered up to LOCAL mode by setting BSI resistor to 3.3kΩ. This causes MCU to wake up directly when battery voltage is supplied.

RTC alarm power up

If phone is in power off mode when an RTC alarm occurs, the wake up follows the procedure described in section Power up and reset. After baseband is powered on, an interrupt is given to MCU. When RTC alarm occurs during power on state, the interrupt for MCU is generated.

A/D channels

The UEMK contains following A/D converter channels that are used for several measurement purposes. The general slow A/D converter is a 10-bit converter using the UEMK interface clock for the conversion. An interrupt is given at the end of the measurement.

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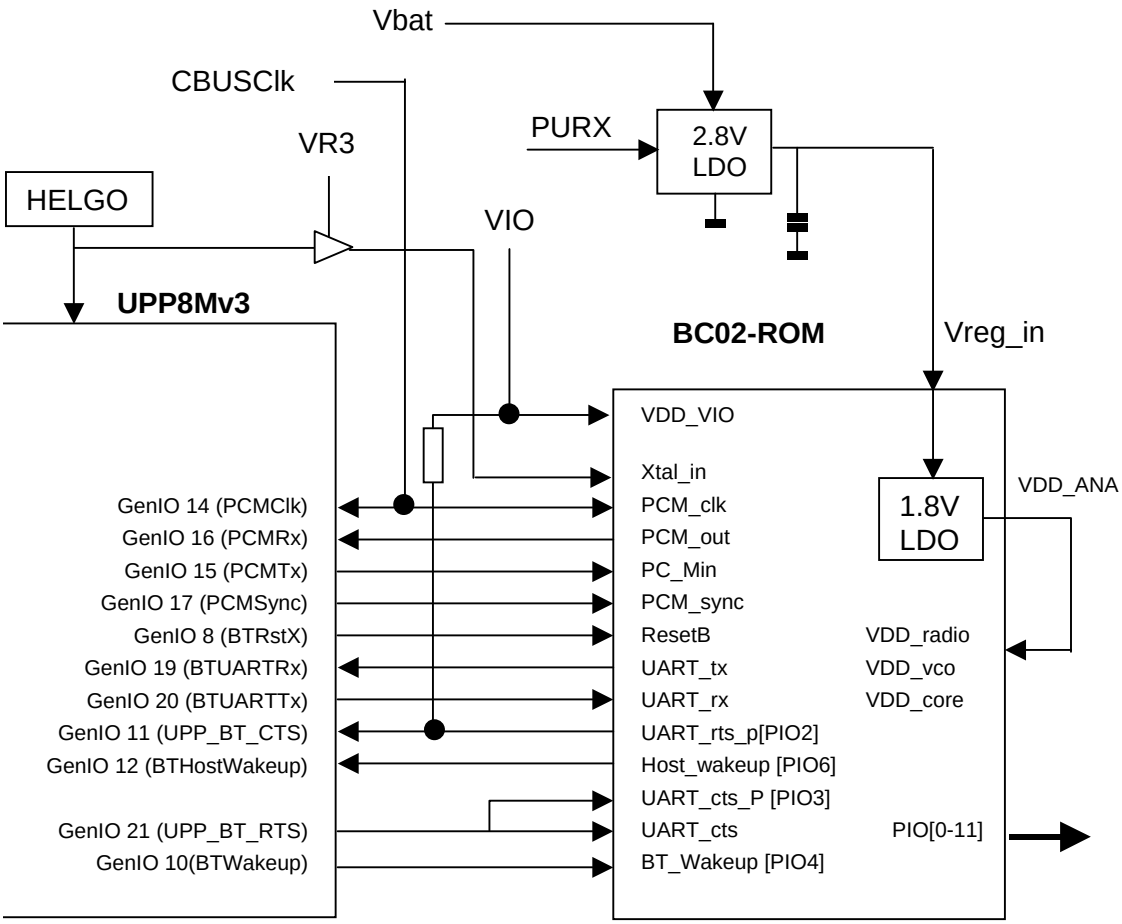
The UEMK's 11-channel analogue to digital converter is used to monitor charging functions, battery functions, user interface and RF functions.

Bluetooth

A single chip bluetooth BC02-ROM is used in RH-26.

Figure 9: Baseband-BT connections



The BB and BC02 interface can be logically divided into audio, user data and control interfaces.

User and control data is transferred through the UART interface. Audio is using a PCM interface of the UPP.

A BC02 internal voltage regulator provides 1.8V supply for the analogue and digital sections of BC02. An external 2.8V regulator is used to ensure that the input voltage to the BC02 internal regulator is within the recommended operating range. VIO is directly used as a supply for IO interface.

Camera

The camera supports a video preview mode with integrated color processing, and high

quality still image mode. The camera module supports the CCP/CCI interface.

Feature	Description		
Resolution	352x288 (physically 360x296)		
Sensor Technology	0.35um HCMOS6i		
Power Consumption Typical @ 23 °C		VDIG (1.8V)	VFLASH2 (2.8V)
	Power Down	<1µA	<1µA
	Sleep	4µA	<1µA
	Viewfinder 15fps (Single-read mode)	18.5mA	6.1mA
Power Supply	Analog Supply voltage (VFLASH2): 2.7V ... 2.9V Digital Supply Voltage (VDIG) 1.7V ... 1.9V (I/O interface)		
Interface	Video Data: CCP Communication: CCI		
On-chip functions	Automatic Exposure Control (AEC)		

The camera module supports a sleep and shutdown functions in order to minimize the current consumption when not used.

In viewfinder mode the device outputs RGB 4:4:4 pixel data for the color LCD display.

Keypads

RH-26 consists of a separate flip board, *TF6*, which includes contacts for the qwerty and T9 keypad domes, MCU, led driver and LEDs for keypad lighting. The flip board is connected to the main PWB through a 3-pin flip connector interface with coaxial cables. Signals of the connector are described in section: *External signals and connections*.

The keyboard of RH-26 consists of qwerty keypads located on the top side of the engine PWB and the FLIP module.

Keypad signals of the engine qwerty keypad are connected to the UPP keyboard interface. The flip keypad is connected to the MCU located in the flip PWB. Key presses are sent to engine through a 2-wire serial interface. The implementation of the engine and flip keypad is similar.

LCD & keyboard illumination

In RH-26, white LEDs are used for LCD and keypad lighting. Three LEDs are used for LCD lighting and on the engine side eight LEDs for qwerty keypad and soft key lighting. A step-up DC-DC converter (LM3500) is used as a LED driver. On the flip module, four LEDs are used for T9 and four LEDs for the qwerty keypad lighting.

LCD LEDs are driven in a serial mode to achieve stable backlight quality. This means constant current flow through LCD LEDs. Serial resistance *Rlcd* is used to define the proper current. The feedback signal, *FB*, is used to control the current. Driver increases or decreases the output voltage for LEDs in order to keep the current stable.

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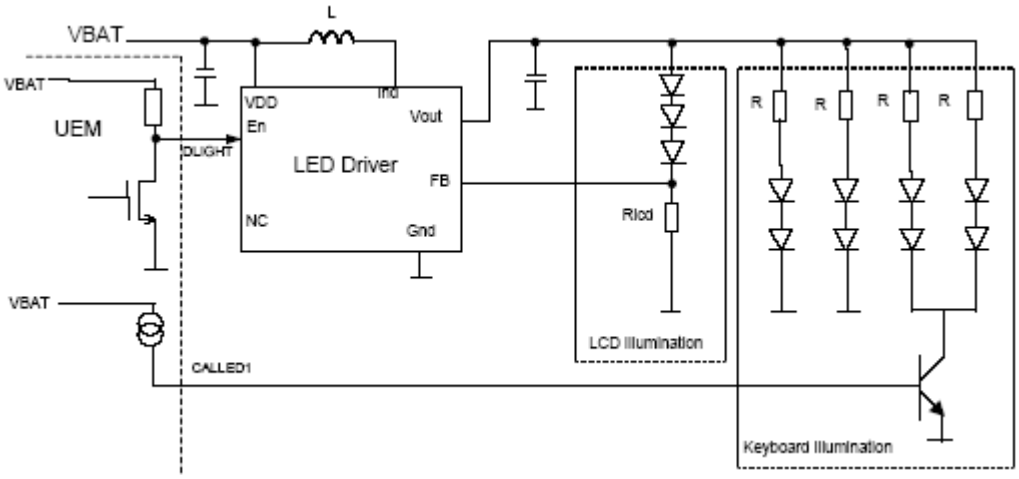
Engine qwerty keypad LEDs are driven in 2 serial mode with each branch having its own current limiting resistor. Serial resistance *R* is used to limit the current through the LEDs. The feedback signal, *FB*, from LCD LEDs controls also the current of keypad LEDs. Qwerty LEDs are controlled through UEMK CALLED1 pin.

Driver is controlled by the UEMK via DLight output. This signal is connected to driver EN-pin (on/off).

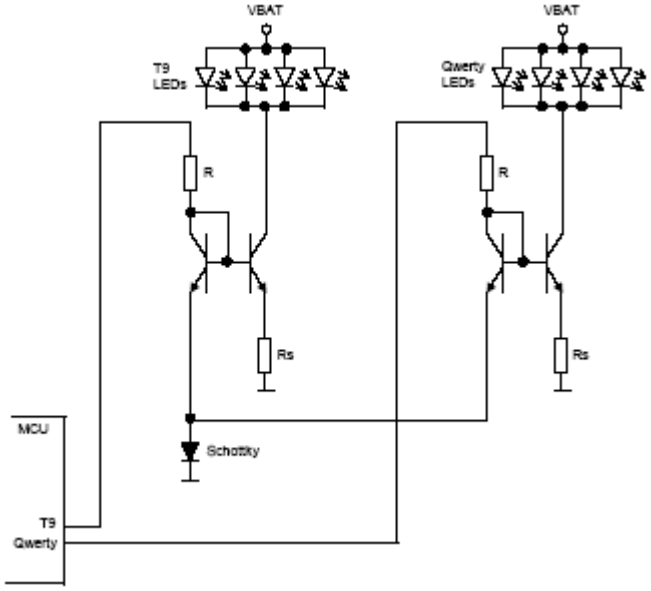
Figure 10: Engine board LCD and keyboard LED connections



On the flip module, there is a transistor based "constant current" circuitry for LED driving. A diode is used to set the reference voltage, and resistors, *Rs*, are used to set the current through transistor and LEDs.

LED drivers are controlled by the MCU I/O-pins. By setting either (qwerty & T9) of the control signals "high", the driver is enabled for the selected keypad.

Figure 11: Flip LED driver circuitry



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LCD

A passive matrix colour STN display having 128 x 128 8 bpp (bits per pixel) is used in RH-26. The LCD display is connected to the transceiver PWB by a board-to-board connector.

Table 21: LCD characteristics

Technology	CSTN
Display format	128 columns x 128 rows
Weight	estimation 7 g
Illumination Mode RAM bit data	Transreflective
	"0000"...OFF (minimum voltages) Black
Numbers of colours	256 (8 bits per pixel, 3 x Red, 3 x Green & 2 x Blue)
Colour filter arrangement	Stripe (RGB)
Pixel height to width ratio	1:1
Main viewing direction	6 o'clock

IR module

The IR interface is designed into the UPP. The IR link supports speeds from 9600 bit/s to 1.152 MBit/s up to distance of 100 cm (75 cm with 1.152Mbit/s). Transmission over the IR if half-duplex.

The length of the transmitted IR pulse depends on the speed of the transmission. When 230.4 kbit/s or less is used as a transmission speed, pulse width is maximum1.63µs. If transmission speed is set to 1.152Mbit/s, the nominal pulse width is 154ns.

Backup battery

A backup battery is used when the main battery is either removed or discharged. The backup battery is used for keeping real-time clock running for a minimum of 10 minutes.

The rechargeable backup battery is connected between UEMK VBACK and GND. In UEMK, the backup battery charging high limit is set to 3.2V. The cut–off limit voltage (V BUCoff–) for the backup battery is 2.0V. Charging is controlled by the MCU by writing into UEMK register.

Cell capacitor SMD "battery" type is used. The nominal capacity of the battery is 0.01 mAh.

Table 22: Backup battery circuitry

Parameter Test conditions	Symbol	Min	Typ	Max	Unit
Back-up battery voltage	VBACK	2.43		3.3	V

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Back-up battery cut-off limit	V_BU_{COFF+} V_BU_{COFF-}	2.04 1.94	2.10 2.0	2.16 2.06	V V
Charging voltage (VBAT ? 3.4V)	VBU	3.1	3.2	3.3	V
Charging current	I_{LIMVBU}	150		500	µA

SIM interface

The UEMK contains the SIM interface logic level shifting. The SIM interface can be programmed to support 3V and 1.8V SIMs. SIM supply voltage is selected by a register in the UEMK. It is only allowed to change the SIM supply voltage when the SIM IF is powered down.

The SIM comparator offset is such that the comparator outputs do not alter state as long as the battery is connected. The threshold voltage is calculated from the battery size specifications.

The whole SIM interface is located in two chips, namely UPP and UEMK.

The SIM interface in the UEMK contains power up/down, port gating, card detect, data receiving, ATR-counter, registers and level shifting buffers logic. The SIM interface is the electrical interface between the Subscriber Identity Module Card (SIM Card) and mobile phone (via UEMK device).

The data communication between the card and the phone is asynchronous half duplex. The clock supplied to the card is in GSM system 3.25 MHz. The data baudrate is SIM card clock frequency divided by 372 (by default), 64, 32 or 16. The supported protocol type, that is T=0 (asynchronous half-duplex character transmission as defined in ISO 7816-3).

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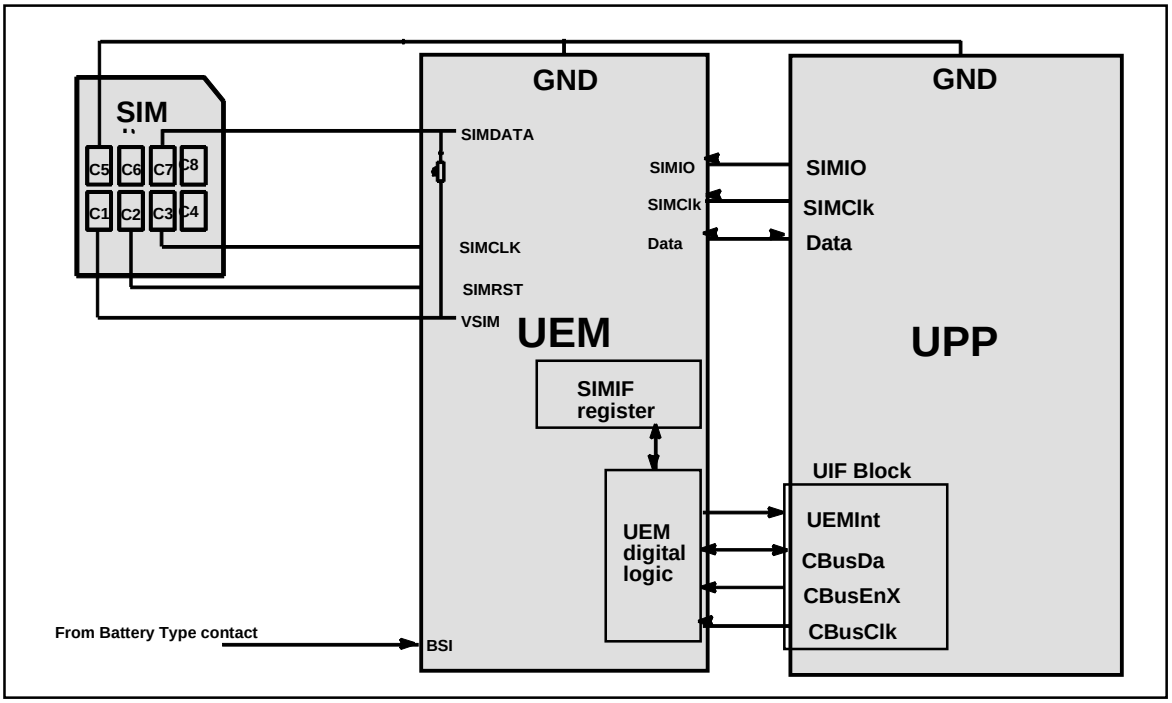
Figure 12: UPP/UEMK SIM interface connections



The internal clock frequency from CTSI block is 13 MHz in GSM. To achieve the minimum starting SIMCardClk rate of 3.25 MHz and the duty cycle requirement between 40% and 60%, the slowest possible clock supplied to the SIM has to be in the GSM system clock rate of 13/4 MHz.

System connector

The system connector in RH-26 is called Pop-Port™ System Connector. It consists of charging plug socket and system connector. In RH-26, the system connector includes:

Function	Note
Charging	Pads for 2 -wire charging in cradles
Audio	- 2 -wire fully differential mono audio output - 2-wire differential microphone input
Power Supply for Accessories	2.78V 70 mA output to accessories (DCT4)
ACI (Accessory Control Interface)	Accessory detection/removal & controlling
FBUS	Standard FBUS

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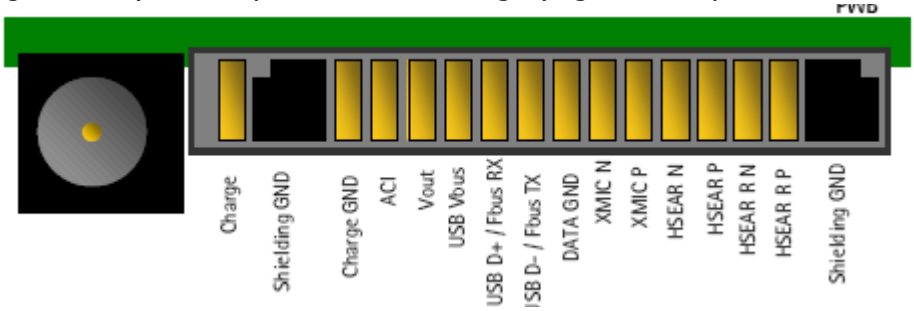
Figure 13: Pop-Port™ system connector (charger plug socket & system connector)



ACI

ACI (Accessory Control Interface) is a point-to-point, bi-directional serial bus. ACI has two main features: **1**) The insertion and removal detection of an accessory device **2**) acting as a data bus, intended mainly for control purposes. A third function provided by ACI is to identify and authenticate the specific accessory which is connected to the system connector interface.

External accessory regulator

An external LDO Regulator is needed for accessory power supply purposes. All ACI-accessories require this power supply. Regulator input is connected to battery voltage VBAT and output is connected to Vout pin in system connector. Regulator is controlled via UPP (On/Off-function).

Figure 14: Accessory power supply diagram

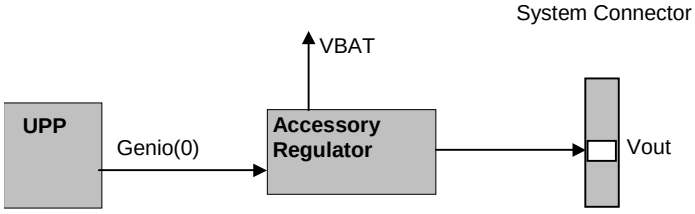


Table 23: Accessory regulator signals

Signal	Min	Nom	Max	Note
Vout	2.70V	2.78	2.86V	I_{max} = 150mA
GenIO(0)	1.4	1.8	1.88 0.6	High (ON) Low (OFF)

External audio

RH-26 is designed to support fully differential external audio accessory connection. A headset can be directly connected to the system connector. Only mono audio is supported. With RH-26, two different kinds of headsets can be used: stereo or mono headset.

Headset implementation uses separate microphone and earpiece signals. The accessory is detected by the HeadInt signal when the plug is inserted. Normally when no plug is present, the internal pull-down on the HF pin pulls down the HeadInt signal. Because of

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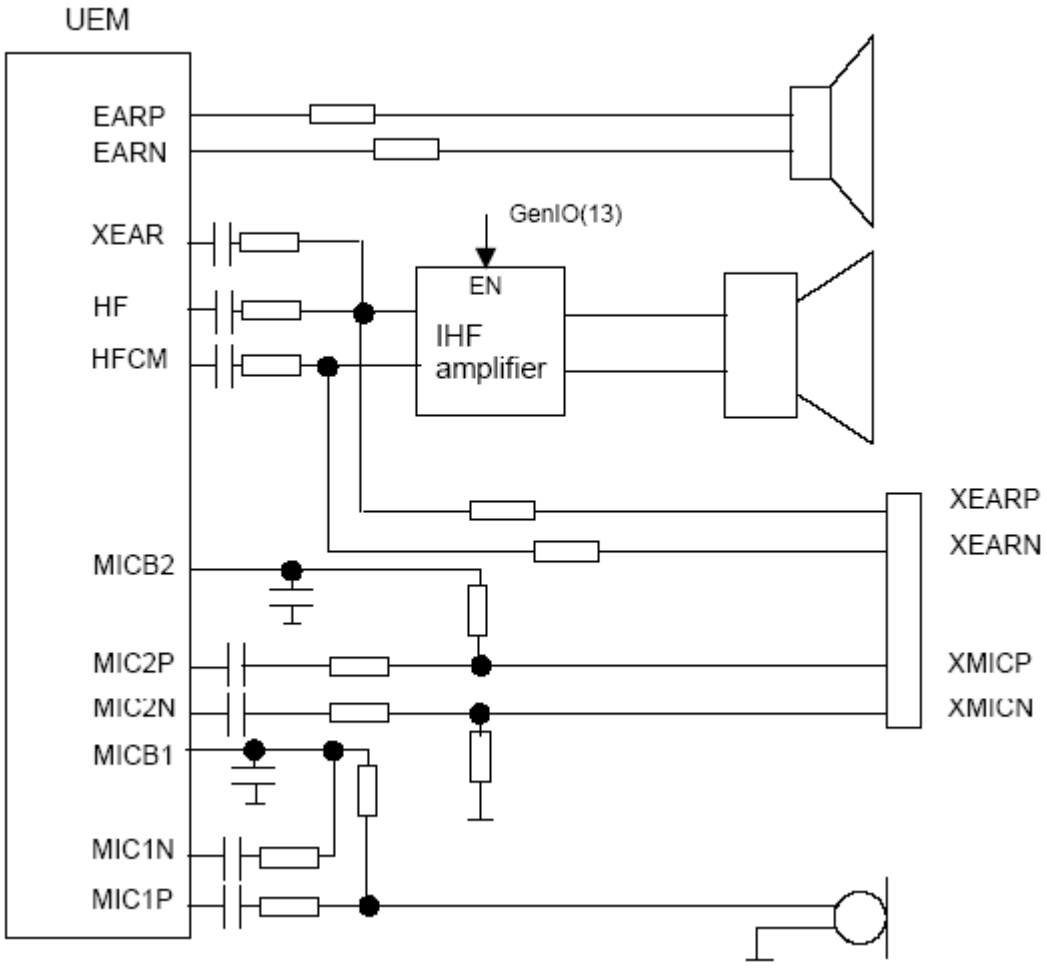
that the comparator level is 1.9V. The HeadInt signal does not change the state, even if the HF output is biased to 0.8V. When the plug is inserted, the switch is opened and the HeadInt signal is pulled up by the internal pull-up. The 1.9V threshold level is reached and the comparator output changes to low state causing an interrupt.

The hook signal is generated by creating a short circuit between the headset microphone signals. In this case, an LP-filter is needed on the HookInt input to filter the audio signal. In this mode, the earpiece signal on the HF and HFCM pins is in opposite phase. The earpiece is driven differentially. When no accessory is present, the HookInt signal is pulled up by the UEMK resistor. When the accessory is inserted and the microphone path is biased, the HookInt signal decreases to 1.8V as a result of the microphone bias current flowing through the resistor. When a button is pressed, the microphone signals are connected together, and the HookInt input gets half of the MicBias DC value 1.1 V. This change in DC level causes the HookInt comparator output to change state, in this case from 0 to 1. The button can be used for answering incoming calls but not for initiating outgoing calls.

Figure 15: RH-26 Audio connections (all components are not shown)



HeadInt comparator reference level is 1.90 V +-0.15 V. HookInt comparator reference is selected, level is 1.35 V.

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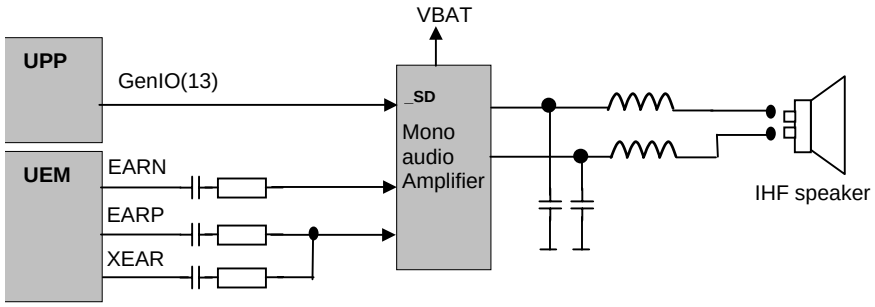
Internal audio

IHF speaker & audio amplifier

Integrated handsfree speaker, 16mm MALT, is used to generate alerting and warning tones in RH-26. IHF speaker is driven by the audio amplifier (LM4890 & NCP2890) external to the UEMK. The speaker capsule is mounted in the antenna assembly. Spring contacts are used to connect the IHF Speaker contacts to the main PWB.

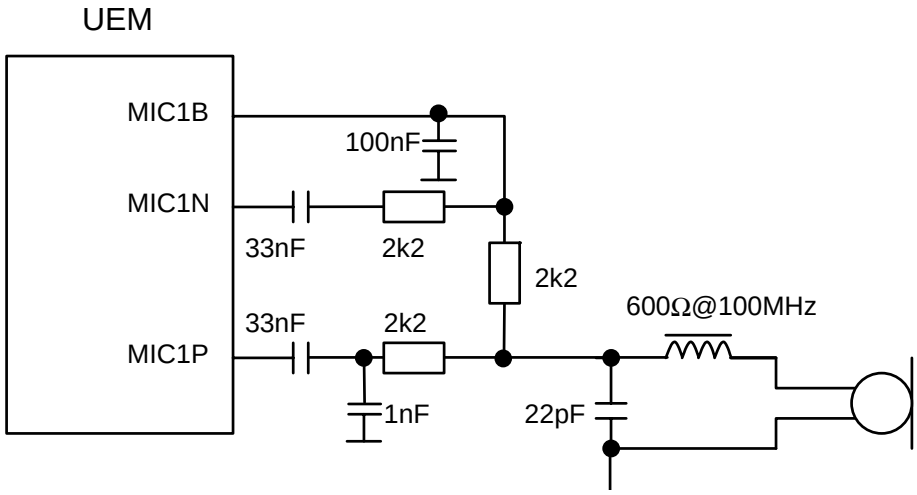
Figure 16: Block diagram of IHF speaker and amplifier



Internal microphone

The internal microphone is connected to the UEMK microphone input. The microphone input is symmetric and microphone bias is provided by the UEMK. The microphone input on the UEMK is ESD protected. Microphone capsule is mounted in the UI Module. Spring contacts are used to connect the microphone contacts to the main PWB.

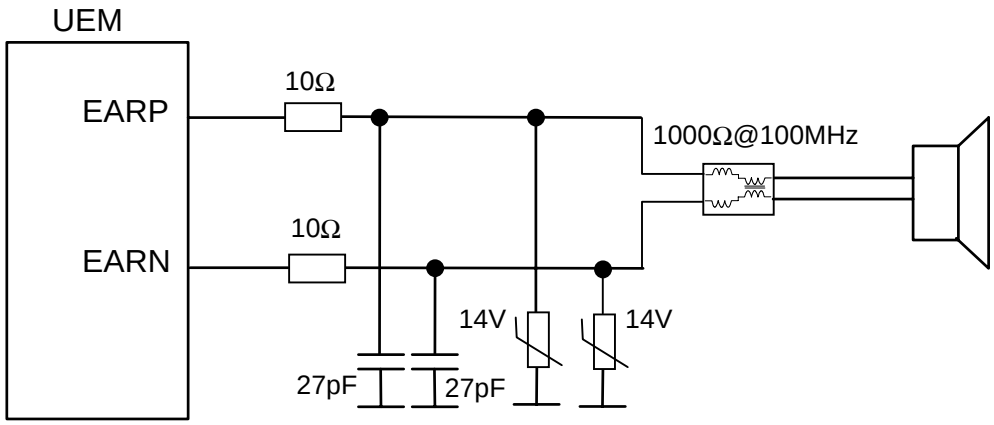
Figure 17: Internal microphone connection



Internal speaker

The internal earpiece is a dynamic earpiece with impedance of 32 ohms. The earpiece must be low impedance, since the sound pressure is generated by using current and not voltage as the supply voltage is restricted to 2.7V. The earpiece is driven directly by the UEMK and the earpiece driver in the UEMK is a bridge amplifier. In RH-26, 8mm PICO type earpiece is used.

Figure 18: Speaker connection



Memory block

For the MCU, UPP includes ROM, 2x4kbytes, that is used mainly for boot code of MCU. To speed up the MCU operation, small 4 kbytes cache is also integrated as a part of the MCU memory interface. For program memory, 8Mbit (512k x 16bit) PDRAM is integrated into the UPP. RAM block can also be used as data memory and it is byte addressable. RAM is mainly for MCU purposes but also DSP has access to it if needed.

RH-26 needs also external RAM to have sufficient RAM capacity. A combo flash is used for that purpose (single package with stacked ICs, 128Mbit flash + 16Mbit pseudo RAM).

MCU code is stored into external flash memory. The size of the flash is 128Mbit (8M x 16bit). The RH-26 baseband supports a burst mode flash with multiplexed address/data bus. Access to the flash memory is performed as a 16–bit access. The flash has read-while-write capabilities which makes the emulation of EEPROM within the flash easy.

RF interface block

The interface between the baseband and the RF can be divided into two categories. Firstly, there is a digital interface from the UPP to the HELGO chip. The interface is used to control the operation of the different blocks in the HELGO chip. This serial interface is also connected to the UEMK. The operation of the RF converters and the RF regulators in then UEMK is controlled by this serial interface. Secondly, there is an analogue interface between the RF and the baseband is connected to the UEMK. The analogue interface consists of RX and TX converter signals. The power amplifier control signal TXC as well as the AFC signal comes from the UEMK. PWB

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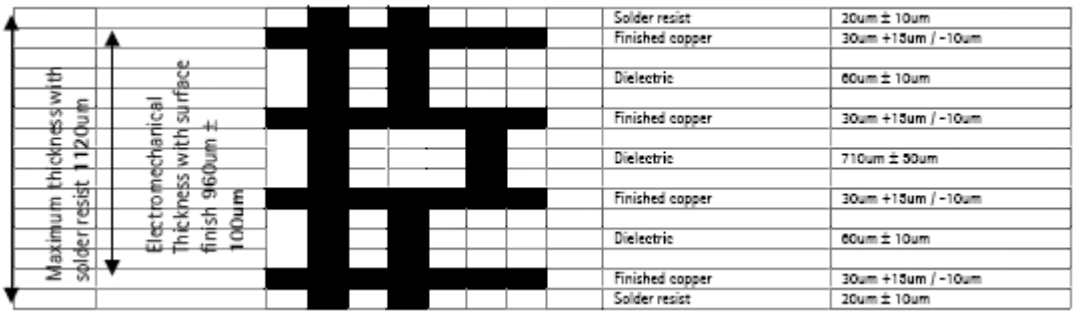
Figure 19: Flip PWB construction



Security

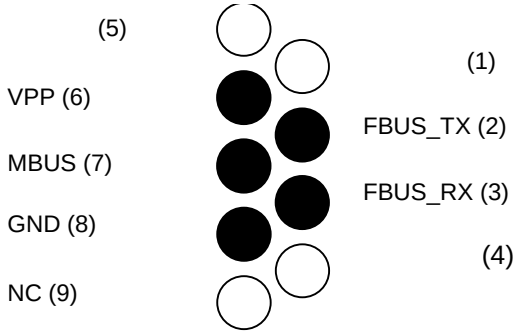
The phone flash program and IMEI codes are software protected using an external security device that is connected between the phone and a PC.

After sales interface

Test pads are placed on the engine PWB for service troubleshooting purposes. The same test pattern is used for after sales purposes as well.

In the pin assignment below, pins numbered 1, 4, and 5 are not in use.

Figure 20: Pin assignment in standard 5-pin production test pattern, PWB view.



FBUS interface

FBUS is an asynchronous data bus having separate TX and RX signals. Default bit rate of the bus is 115.2 kbit/s. FBUS can also be accessed via system connector.

MBUS Interface

MBUS interface is used for controlling the phone in R&D and AS. It is a bi-directional serial bus between the phone and PC. The phone initialization is made using MBUS. The default transmission speed is 9.6 kbit/s.

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RF

This section presents the electrical specifications of the GSM850/GSM1800/GSM1900 triple band transceiver, RH-26. The section contains electrical specifications, functional descriptions and block diagrams. The RF requirements follow ETSI GSM850/GSM1800/ GSM1900 phase2+ specifications.

The module is supporting GPRS, EGPRS, and HSCSD protocols. GPRS multislot class in 10 and HSCSD multislot class is 6. EGPRS multislot classes are 1 - 2. Power class in EGSM850 mode is 4 (33 dBm output power) and 1 in 1800/1900 bands (30 dBm). In 8-PSK (EDGE) -mode power class is E2 (27 dBm in 850 band, and 26 dBm in 1800 and 1900 bands). Multislot power class in EGSM850 is 5 and in GSM1800/1900 bands 1.

The operating temperature range for all the components is from -10 to +80 C° unless otherwise mentioned in the specifications.

The RF module performs the necessary high frequency operations of the GSM850/ GSM1800/GSM1900 triple band engine. Both the transmitter and receiver have been implemented by using direct conversion architecture.

Another core component is a power amplifier module which includes two amplifier chains, one for GSM850 and the other for GSM1800/GSM1900. Other key components are a 26 MHz VCTCXO (voltage controlled temperature compensated crystal oscillator) for frequency reference, 3420-3980 MHz SHF VCO (super high frequency voltage controlled oscillator), a front end module with a RX/TX switch with internal SAW filters (EGSM850 and GSM1800), and one additional SAW filter and one balun for GSM1900 band. GSM850 and GSM1800 LNAs (low noise amplifier) for the receiver front-end are integrated in Helgo, while GSM1900 LNA is external.

The control information for the RF is coming from the baseband section of the engine through a serial bus, referred to later on as the RFBus. This serial bus is used to pass the information about the frequency band, mode of operation, and synthesizer channel for the RF. In addition, exact timing information and receiver gain settings are transferred through the RFBus. Physically, the bus is located between the baseband ASIC called UPP and Helgo. Using the information obtained from the UPP, Helgo controls itself to the required mode of operation and further sends control signals to the front end and power amplifier modules. In addition to the RFBus there are still other interface signals for the power control loop and VCTCXO control and for the modulated waveforms.

The RF module takes care of all RF functions of the engine. RF circuitry is located on the double side of the 8-layer PWB. PWB area for the RF circuitry is 8.7 cm^2.

EMC leakage is prevented by using metal cans. The RF circuits are separated into three blocks. The first includes the PA and TX 850band SAW. The second includes the front end module, 1900 LNA and 1900 band SAW. The last block includes the Helgo RF IC, VCO, VCTCXO and baluns. The RF transmission lines are made with striplines.

The RF transmission lines are made by striplines and microstriplines after PA.

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The baseband circuitry is located on the other side of the board, which is shielded with a metallized frame and ground plane of the UI-board.

Maximum height of the RF components on the PWB is 1.8 mm. Heat generated by the circuitry is carried off via the PWB ground planes and metallic shields.

Main technical specifications

Nominal and maximum ratings

Parameter	Rating
Battery voltage nominal	3.7 V
Battery voltage maximum	4.2 V
Battery voltage minimum	3.1 V *)
Regulated supply voltage	2.78+/-3% V
Voltage reference	1.35+/-1.2% V
Operating temperature range	-10...+55 C^o
	-25...+70 C^o reduced performance, no damage

*) Normal cut off battery voltage is 3.04V but minimum battery voltage level for RF is 2.95V.

RF frequency plan

The VCO operates at the channel frequency multiplied by two or four depending on the frequency band of operation. This means that the baseband modulated signals are directly converted up to the transmission frequency and the received RF signals directly down to the baseband frequency. In addition, the circuit implementation of the frequency dividers in an integrated circuit offers a good topology for 90 degrees phase shifter which is needed in the IQ-modulator and -demodulator.

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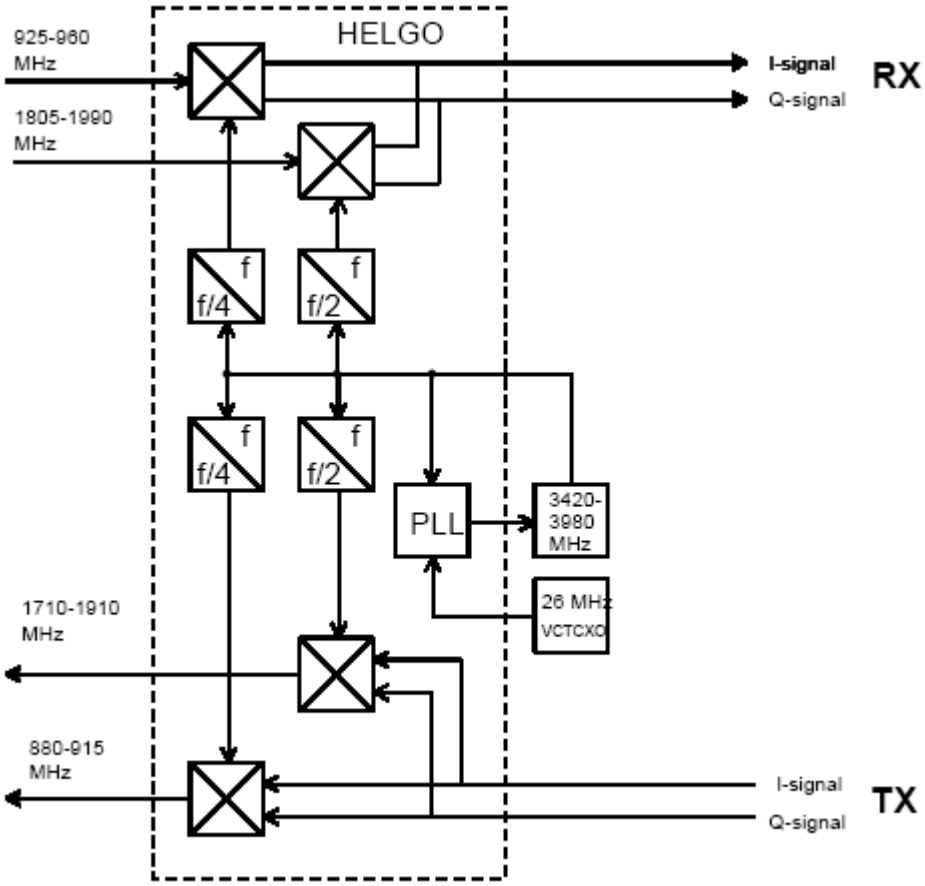
Figure 21: RF frequency plan



DC characteristics

Regulators

The transceiver baseband section has a multi-function analogue ASIC, UEM, which contains six pieces of 2.78 V linear regulators and a 4.8 V switching regulator. All the regulators can be controlled individually by the 2.78 V logic directly or through a control register. Normally, direct control is needed because of the switching speed requirement: the regulators are used to enable the RF-functions which means that the controls must be fast enough.

The use of regulators can be seen in the power distribution diagram. The seven regulators are named from VR1 to VR7. VrefRF01 is used as the reference voltage for Helgo, VrefRF01 (1.35V) for the bias reference.

The regulators (except for VR7) are connected to Helgo. Different modes of operation can be selected inside Helgo according to the control information coming through the RFBus.

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Typical current consumption.

Operation mode	Current consumption	Notes
Power OFF	< 10uA	Leakage current (triple band PA)
RX, GSM850	75 mA, peak	
RX, GSM 1800/GSM1900	70 mA, peak	
TX, power level 5, GSM850	2500 mA, peak	
TX, power level 0, GSM 1800/ GSM1900	1100 mA peak	

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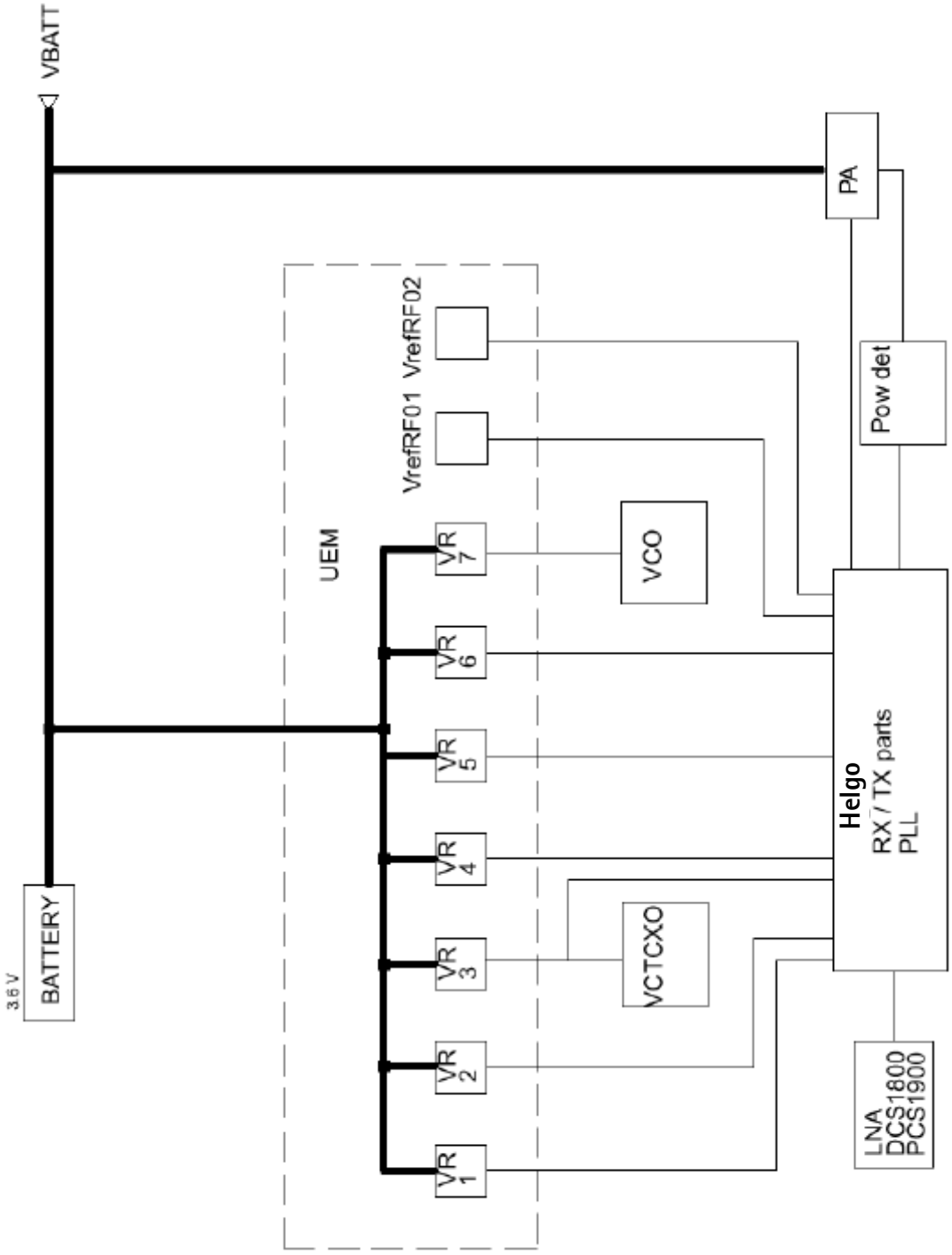
Figure 22: Power distribution diagram



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RF characteristics

Channel numbers and frequencies

System	Channel number	TX frequency	RX frequency	Unit
GSM900	0 < =n <=124	F = 890 + 0.2 * n	F = 935 + 0.2 * n	MHz
	975<= n <= 1023	F= 890+0.2* (n -1024)	F= 935+0.2* (n -1024)	MHz
GSM1800	512 <= n <= 885	F=1710.2+0.2*(n-512)	F=1805.2+0.2*(n-512)	MHz
GSM1900	512 <= n <=810	F=1850.2+0.2*(n-512)	F=1930.2+0.2*(n-512)	MHz

Main RF characteristics

Item	Values (GSM900 / GSM1800/GSM1900)
Receive frequency range	925 ... 960 MHz / 1805...1880 MHz / 1930 ... 1990 MHz
Transmit frequency range	880 ... 915 MHz / 1710 ... 1785 MHz / 1850 ... 1910 MHz
Duplex spacing	45 MHz / 95 MHz / 80 MHz
Channel spacing	200 kHz
Number of RF channels	174 / 374 / 300
Power class GSMK	4 (2 W) / 1 (1 W) / 1 (1 W)
Power class 8-PSK	E2: (27 / 26 / 26 dBm)
Number of power levels GSMK	15 / 16 / 16
Number of power levels 8-PSK	12 / 14 / 14

TX characteristics

Item	Values (GSM900/GSM1800/GSM1900)
Type	Direct conversion, nonlinear, FDMA/TDMA
LO frequency range	3520...3660 MHz / 3420...3570 MHz 3700...3820 MHz
Output power GMSK	2 W / 1 W peak
Output power 8-PSK	0.5 W / 0.4 W peak
Gain control range	min. 30 dB
Maximum phase error (RMS/peak) GMSK	max 5 deg./20 deg. Peak
Maximum EVM (RMS/peak) 8-PSK	max 10% / 30%

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RX characteristics

Table 24: Receiver characteristics

Item	Values, GSM900/GSM1800/GSM1900
Type	Direct conversion, Linear, FDMA/TDMA
LO frequencies	3700...3840 MHz / 3610...3760 MHz / 3860...3980 MHz
Typical 3 dB bandwidth	+/- 91 kHz
Sensitivity	min. - 102 dBm
Total typical receiver voltage gain (from antenna to RX ADC)	86 dB
Typical AGC dynamic range	83 dB
Accurate AGC control range	60 dB
Typical AGC step in LNA	30 dB GSM1800/GSM1900 25 dB GSM900
Usable input dynamic range	-102 ... -10 dBm
RSSI dynamic range	-110 ... -48 dBm
Compensated gain variation in receiving band	+/- 1.0 dB

RF block diagram

The block diagram of the RF module can be seen in the figure below. The detailed functional description is given in the following sections.

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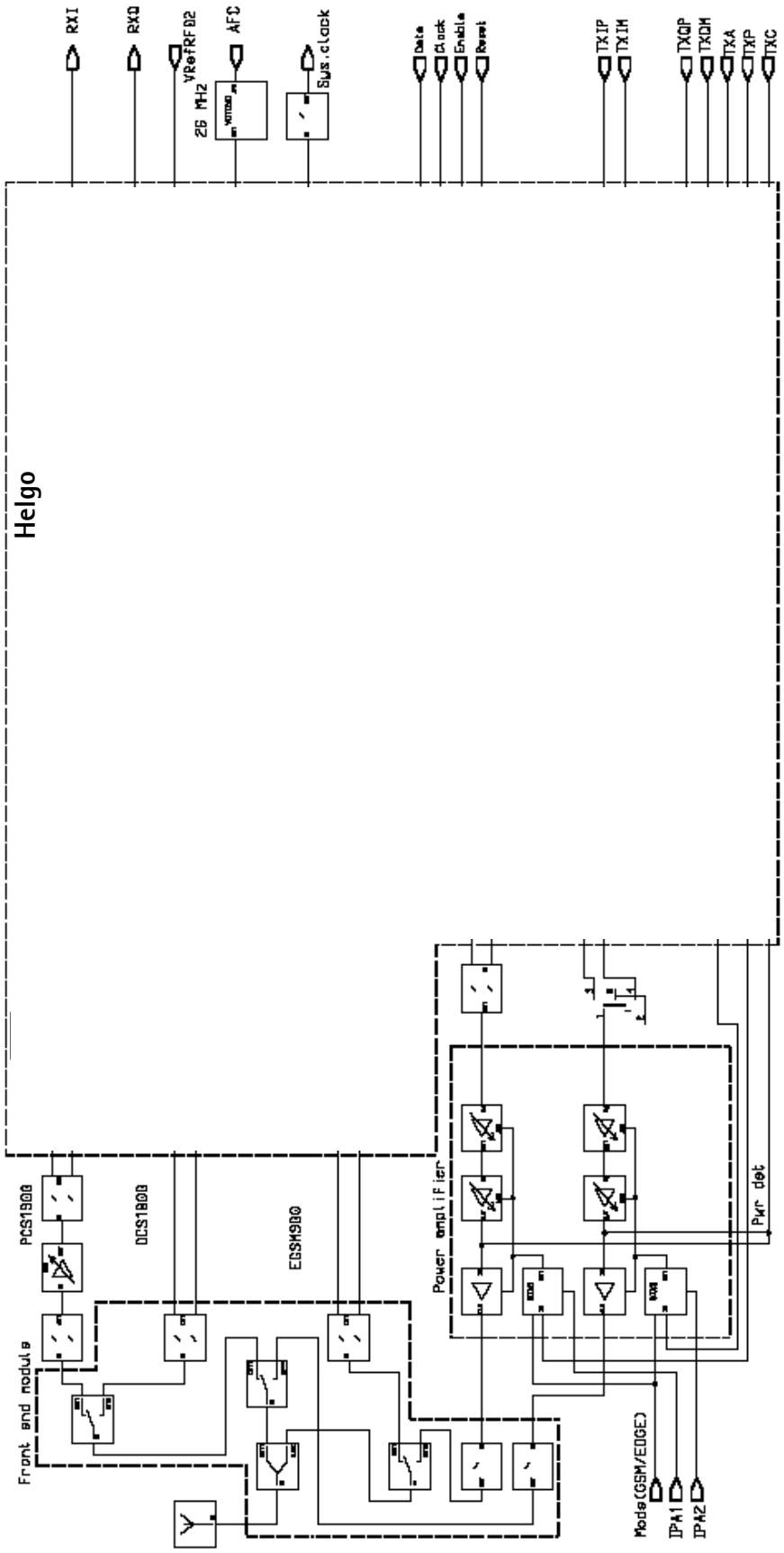
Figure 23: RF block diagram.



Receiver

Each receiver path is a direct conversion linear receiver. From the antenna, the received RF-signal is fed to a front end module where a diplexer first divides the signal into two separate paths according to the band of operation: either lower, GSM850 or upper, GSM1800/GSM1900 path. Each of the paths follows a pin-diode switch which is used to select either a receive or transmit mode. At the upper band in the receive mode, either GSM1800 or GSM1900 path is further selected by another pin-diode switch. The selections are controlled by Helgo, which obtains the mode/band and timing information through the RFBus. After the front end module there is a SAW filter at each of the receiver paths. Then, the signal is fed to the LNAs which are integrated in Helgo in GSM850 and GSM1800 while in GSM1900 the LNA is external. In GSM1900 the amplified signal is fed to balun and after that to a pregain stage of the mixer, while in GSM850 and GSM1800 the signals are connected directly to the LNA's and after that to the pregain stages. The pregain stages as well as all the following receiver blocks are integrated in Helgo. The LNAs have three gain levels. The first one is the maximum gain, the second one is about 30 dB below the maximum, and the last one is the off state level.

After the pregain stages there are demodulator mixers at each signal path to convert the RF signal directly down to baseband I and Q signals. Local oscillator signals for the mixers are generated by an external VCO. The frequency is divided by two in GSM1800 and GSM1900 and by four in GSM850. Those frequency dividers are integrated in Helgo. They provide accurate phase shifting by 90 degrees which is needed for the demodulator mixers.

The demodulator output signals are all differential. After the demodulators, there are amplifiers called DtoS (differential to single ended) which convert those differential signals to single ended. Before that, they combine the signals from the three demodulators to a single path which means that from the output of the demodulators to the baseband interface there are just two signal paths (I and Q) which are common to all the frequency bands of operation. In addition, the DtoS amplifiers perform the first part of the channel filtering and AGC (automatic gain control): they have two gain stages, the first one with a constant gain of 12 dB and 85 kHz -3 dB bandwidth and the second one with a switchable gain of 6 dB and -4 dB. The filters in the DtoS blocks are active RC filters. The rest of the analogue channel filtering is provided by blocks called BIQUAD which include modified Sallen-Key biquad filters.

After the DtoS and BIQUAD blocks there is another AGC-amplifier which provides a gain control range of 42 dB in 6 dB steps.

In addition to the AGC steps, the last AGC stage also performs the real time DC offset compensation which is needed in a direct conversion receiver to cancel out the effect of the local oscillator leakage. DC offset compensation is performed during the operations called DCN1. DCN1 is carried out by charging large off-chip capacitors in the last AGC stages to a voltage which causes a zero DC offset.

After the last AGC and DC offset compensation stages, the single ended and filtered I- and Q-signals are finally fed to the RX ADCs. The maximum peak-to-peak voltage swing

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for the ADCs is 1.45 V.

Transmitter

In contrast to the receiver where the adaptation to the modulation (GMSK) is performed by the DSP algorithm, the transmitter must be configured differently also as regards the hardware. The selected modulation scheme affects the operation of the IQ-modulator, power control loop, and the power amplifier biasing.

Generally, the transmitter consists of two final frequency IQ-modulators and power amplifiers, for the lower and upper bands separately, and a power control loop. The IQ-modulators are integrated in Helgo, as well as the operational amplifiers of the power control loop. The two power amplifiers are located in a single module and the power detector, directional coupler, and loop filter parts of the power control loop are implemented as discrete components on the PCB. In the GMSK mode, the power is controlled by adjusting the DC bias levels of the power amplifiers.

The modulated waveforms, the I- and Q-signals, are generated by the baseband part of the engine module. After postfiltering, implemented as RC-networks, waveforms are transferred into the IQ-modulator. Local oscillator signals for the modulator mixers are generated by an external VCO the frequency of which is divided by two in GSM1800 and in GSM1900 and by four in GSM850. Those frequency dividers are integrated in Helgo and in addition to the division they also provide accurate phase shifting by 90 degrees which is needed for the modulator mixers.

At the upper band there is a dual mode buffer amplifier at the output of the IQ-modulator. In the GMSK mode it acts as a buffer amplifier while in the 8-PSK mode it is used as a voltage variable attenuator.

The final amplification is realised by a three stage power amplifier. There are two different amplifier chains in a single amplifier module, one for GSM850 and one for GSM1800/GSM1900. The lower band power amplifier is able to deliver over 2 W of RF power, while the capability of the upper band amplifier is over 1 W. In the GMSK mode, the gain control is implemented by adjusting the bias voltages of the first two transistor stages, reaching the dynamic range of over 70 dB. In the 8-PSK mode, the biases are fixed and they are set higher than in the GMSK mode to meet the more demanding linearity requirements.

After the power amplifier, the signal goes through a low pass filter and a pin-diode switch which is used to select between the reception and transmission. Finally, the two signal paths, lower and upper band, are combined in a diplexer after which the signal is routed through an antenna connector to the antenna.

Connections

Antenna

The GSM850/GSM1800/GSM1900 transceiver uses internal antenna.

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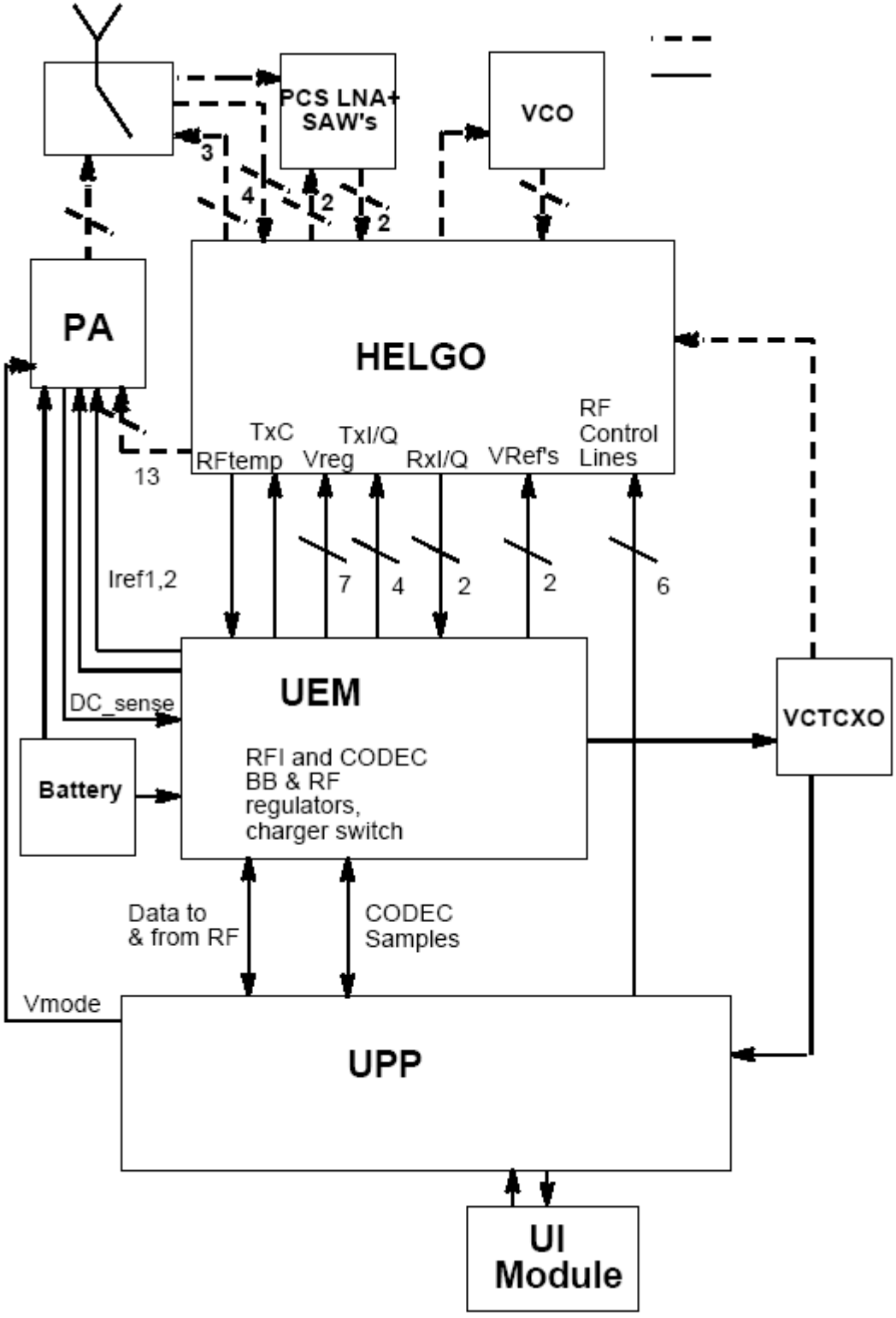
RF-BB interface

Figure 24: Engine block diagram



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